

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	24789	(detect\$3 or sens\$3 or monitor\$3 or track\$3) near5 ((travel\$3 or mov\$5) near3 (vehicle or car or automobile))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:17
L2	2131	1 and (CCD or camera)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:18
L3	17731	(CCD or camera) near5 (connect\$3 or coupl\$3 or link\$3) near7 (computer or center or central or \$4process\$3 or control\$3)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:03
L4	236351	(detect\$3 or sens\$3) near5 (speed or velocity)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:05
L5	61323	(detect\$3 or sens\$3) near5 (accelerat\$3)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:06
L6	28624	(detect\$3 or sens\$3) near5 emission	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:06
L7	1	2 and 3 and 4 and 5 and 6	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:28
L8	1	7 and port	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:57
L9	19	2 and 3 and (communicat\$3 near2 port)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:50
L10	0	9 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:13
L11	0	2 and 3 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:14
L12	0	2 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:15
L13	0	1 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:34
L14	996	('100' or '200' or '400') near2 megabits	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:16
L15	13	14 and (detect\$3 or sens\$3 or monitor\$3 or track\$3) near9 (vehicle or car or automobile)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:21

L16	3	15 and (CCD or camera)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:24
L17	4	9 and (IEEE or (serial near2 bus))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:30
L18	0	7 and (IEEE or (serial near2 bus))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 12:33
L19	34	2 and 3 and (IEEE or (serial near2 bus))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:30
L20	16	(8 or 15 or 19) and ((second or two) near4 (CCD or camera))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:22
L21	582	((first or '1') near2 (CCD or camera)) near4 (connect\$3 or coupl\$3) near4 ((second or '2') near2 (CCD or camera))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:54
L22	2	20 and 21	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 09:58
L23	13	2 and 21	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:07
L24	2	("6230087").PN.	USPAT; EPO; JPO; DERWENT	OR	OFF	2005/08/16 10:06
L25	13	1 and 21	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:07
L26	140651	(position or location) near4 (vehicle or car or automobile)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:21
L27	30	(8 or 15 or 19) and 26	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:22
L28	84	2 and 3 and (4 or 5 or 6)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:28
L29	18	28 and 26 and (communicat\$3 near2 port)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:42
L30	0	21 and 29	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:33
L31	0	29 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 13:09

L32	438	340/937.ccls.	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:35
L33	16	28 and 26 and 32	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:52
L34	1	33 and (communicat\$3 near2 port)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:51
L35	0	14 and 33	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:52
L36	2	21 and 33	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 10:53
L37	6	(29 or 33) and (IEEE or (serial near2 bus))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 12:33
L38	0	33 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 13:05
L39	0	1 and 3 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 13:09
L40	12	3 and (('100' or '200' or '400') near2 megabits)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/08/16 13:09

US 6307201 B1

Method and apparatus 250/339.1; 250/338.5

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US 5978804 A	Natural products inform	707/10	707/104.1; 715/500.1
US 6297897 B1	Method and arrangement	398/122	398/123; 398/152; 398/9
US 4749254 A	Optical sensor system	385/12	367/141; 374/143; 385/4; 73/170.

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US 6711474 B1	Automobile personal c 701/1	455/414.1; 455/456.1; 701/210
US 6526335 B1	Automobile personal c 701/1	307/10.1; 342/357.1; 701/36
US 5893043 A	Process and arrangen 701/207	246/182C; 246/187C; 701/209; 701/210
US 6931596 B2	Automatic positioning 715/728	345/649; 715/863
US 6880756 B2	METHOD OF SPECKI 235/462.0	235/462.25; 235/472.01
US 6863216 B2	METHOD OF SPECKI 235/462.0	235/462.25; 235/472.01
US 6857570 B2	METHOD OF SPECKI 235/462.0	235/462.25; 235/472.01
US 6850628 B2	Lane recognition app 382/104	701/28
US 6823241 B2	Lane recognition app 701/1	
US 6816184 B1	Method and apparatus 348/143	
US 6768944 B2	Method and system fo 701/301	213/36
US 6739511 B2	METHOD OF SPECKI 235/462.0	235/462.25; 235/472.03
US 6720920 B2	Method and arrangem 342/386	342/357.06
US 6718049 B2	Near-infrared disguise 382/115	348/164; 348/169
US 6678413 B1	System and method fo 382/181	348/169
US 6624611 B2	Sensing vehicle batter 320/104	
US 6548982 B1	Miniature robotic vehi 318/568.1	318/568.12; 446/435; 446/457; 446/458
US 6546119 B2	Automated traffic viol 382/104	701/119
US 6539931 B2	Ball throwing assistan 124/34	124/32; 124/6; 124/78
US 6496117 B2	System for monitoring 340/576	340/521; 340/575; 348/77
US 6424273 B1	System to aid a driver 340/937	340/435; 340/436; 340/903; 340/904
US 6424272 B1	Vehicular blind spot vi 340/937	340/435; 340/436; 340/936; 701/119
US 6314364 B1	Mobile interactive wor 701/200	340/995.13; 701/213
US 6233007 B1	Method and apparatus 348/157	348/169; 348/579
US 6194860 B1	Mobile camera-space 318/587	318/586; 700/254; 700/259; 901/119
US 6166744 A	System for combining 345/629	345/421; 345/633
US 5986543 A	Programmable vehicle 340/426.1	340/426.14; 340/5.31; 340/5.33; 340/5.35
US 5938717 A	Speed detection and i 701/117	340/937; 701/119; 701/96
US 5761326 A	Method and apparatus 382/103	340/937; 348/148; 382/104; 382/105
US 5682133 A	Programmable vehicle 340/426.1	340/425.5; 340/5.33; 340/5.81; 340/5.83
US 5559695 A	Apparatus and metho 701/1	345/501; 348/219.1; 348/355; 700/259
US 5557254 A	Programmable vehicle 340/426.1	340/5.31; 340/5.33; 340/5.53; 340/5.55
US 5434927 A	Method and apparatus 382/104	348/148; 382/159; 382/199; 706/119
US 5083200 A	Method for identifying 348/148	340/942; 348/26; 702/142; 702/143

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US 6314364 B1
US 6718049 B2

Mobile interactive wor 701/200 340/995.13; 701/213
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US 6314364 B1	Mobile interactive wor	701/200	340/995.13; 701/213
US 5698861 A	System for detecting	250/559.29	250/206.1; 250/559.32; 348/262
US 5642299 A	Electro-optical range	1702/142	340/937; 356/3; 356/4.01; 382/10
US 6894606 B2	Vehicular black box m	340/435	340/436; 340/437; 340/439; 340/4
US 6868168 B2	Lane recognition syst	382/104	340/933; 348/113
US 6755701 B2	Amphibious vehicle w	440/36	37/307
US 6748302 B2	Lane tracking control	701/1	340/937; 701/28; 701/301; 701/4
US 6718049 B2	Near-infrared disguise	382/115	348/164; 348/169
US 6489887 B2	Lane-keep assisting s	340/436	340/435; 340/937; 348/148; 701/4
US 6163338 A	Apparatus and metho	348/148	348/143
US 5793420 A	Video recording syste	348/148	340/433; 348/151
US 5586063 A	Optical range and spe	702/142	324/160; 340/936; 340/937; 356/4
US 5208750 A	Control System for un	701/28	180/168; 340/988; 348/119

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US 6681195 B1	Compact speed meas 702/142	700/159; 701/119; 702/143; 702/
US 6923374 B2	Neutron-beam based 235/454	235/462.14; 235/462.15
US 6918541 B2	Object identification al	235/462.0' 235/462.25
US 6915954 B2	Programmable data el	235/462.0' 235/462.25
US 6913202 B2	Planar laser illuminati	235/472.0' 235/462.01; 235/462.25; 235/462
US 6880756 B2	METHOD OF SPECKI	235/462.0' 235/462.25; 235/472.01
US 6877662 B2	Led-based planar ligh	235/462.0' 235/462.25; 235/472.01
US 6863216 B2	METHOD OF SPECKI	235/462.0' 235/462.25; 235/472.01
US 6857570 B2	METHOD OF SPECKI	235/462.0' 235/462.25; 235/472.01
US 6851610 B2	Tunnel-type package	235/462.0' 235/472.01
US 6837432 B2	METHOD OF AND AF	235/462.0' 235/462.25; 235/472.01
US 6830185 B2	Method of and system	235/462.0' 235/472.01
US 6830184 B2	METHOD OF AND AF	235/462.0' 235/462.25; 235/472.01
US 6827265 B2	Automatic vehicle ider	235/462.0' 235/462.25; 235/472.01
US 6739511 B2	METHOD OF SPECKI	235/462.0' 235/462.25; 235/472.03
US 5815093 A	Computerized vehicle	340/937 340/426.15; 340/426.19; 340/426
US RE31023 E	Highly automated agri	405/37 137/236.1; 137/386; 137/79; 138/
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US 6919823 B1	Image recording appa	340/937	340/916; 340/933; 340/938
US 6140941 A	Open road cashless t	340/928	235/384; 340/937; 348/149; 701/
US 5809161 A	Vehicle monitoring sy	382/104	340/937; 348/149; 382/103
US 5742699 A	Passive velocity meas	382/107	340/936; 340/937; 348/137; 348/
US 6812831 B2	Vehicle surroundings	340/435	340/903; 340/937; 348/148
US 6748302 B2	Lane tracking control	: 701/1	340/937; 701/28; 701/301; 701/4
US 6704653 B2	Vehicle backing supp	701/301	340/425.5; 340/937; 340/988; 348
US 6489887 B2	Lane-keep assisting s	340/436	340/435; 340/937; 348/148; 701/
US 6472977 B1	Method for the display	340/425.5	340/426.1; 340/426.28; 340/435;
US 6298290 B1	Memory apparatus for	701/35	340/937; 701/45
US 6057754 A	Drive assist system fo	340/435	340/436; 340/903; 340/937; 348/
US 5938717 A	Speed detection and i	701/117	340/937; 701/119; 701/96
US 5935190 A	Traffic monitoring syst	701/119	340/936; 340/937; 342/104; 342/
US 5815093 A	Computerized vehicle	340/937	340/426.15; 340/426.19; 340/426
US 5761326 A	Method and apparatus	382/103	340/937; 348/148; 382/104; 382/
US 4214265 A	Method and device fo	348/149	340/937

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